

7.3 Exercises - Solutions

Problem 1 Apply the eigenvalue method of this section to find a general solution of the given system:

$$x_1' = x_1 - 5x_2, \quad x_2' = x_1 + 3x_2.$$

Solution: $\mathbf{A} = \begin{bmatrix} 1 & -5 \\ 1 & 3 \end{bmatrix}$. So: $|\mathbf{A} - \lambda I| = \begin{vmatrix} 1 - \lambda & -5 \\ 1 & 3 - \lambda \end{vmatrix} = (1 - \lambda)(3 - \lambda) + 5 = \lambda^2 - 4\lambda + 8$.

$\lambda = \frac{4 \pm \sqrt{16 - 32}}{2}$. **Eigenvalues:** $\lambda = 2 \pm 2i$. **Eigenvector Equation (for $2 + 2i$):**

$$\begin{bmatrix} 1 - (2 + 2i) & -5 \\ 1 & 3 - (2 + 2i) \end{bmatrix} \Rightarrow \begin{bmatrix} -1 - 2i & -5 \\ 1 & 1 - 2i \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 - 2i \\ -1 - 2i & -5 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 1 - 2i \\ 0 & 0 \end{bmatrix}, \quad y = b, \quad x = -b(1 - 2i)$$

Eigenvector: $\vec{v} = \begin{bmatrix} -b(1 - 2i) & b \end{bmatrix}^T = \begin{bmatrix} 1 - 2i & -1 \end{bmatrix}^T$, when $b = -1$.

So we have: $\vec{v}e^{(2+2i)t}$ (Notationally manipulate into the form $f(t) + ig(t)$)

$$= e^{2t}e^{2it} \begin{bmatrix} 1 - 2i \\ -1 \end{bmatrix} = e^{2t}(\cos 2t + i \sin 2t) \begin{bmatrix} 1 - 2i \\ -1 \end{bmatrix} = e^{2t} \begin{bmatrix} (\cos 2t + i \sin 2t)(1 - 2i) \\ -\cos 2t - i \sin 2t \end{bmatrix}.$$

Expanding the parentheses:

$$= e^{2t} \begin{bmatrix} (\cos 2t + i \sin 2t) - 2i(\cos 2t + i \sin 2t) \\ -\cos 2t - i \sin 2t \end{bmatrix} = e^{2t} \begin{bmatrix} \cos 2t + i \sin 2t - 2i \cos 2t + 2 \sin 2t \\ -\cos 2t - i \sin 2t \end{bmatrix}.$$

Collecting the imaginary parts:

$$= e^{2t} \begin{bmatrix} \cos 2t + 2 \sin 2t + i(\sin 2t - 2 \cos 2t) \\ -\cos 2t - i \sin 2t \end{bmatrix}.$$

Separating the imaginary part from the real part ($f(t) + ig(t)$):

$$= e^{2t} \begin{bmatrix} \cos 2t + 2 \sin 2t \\ -\cos 2t \end{bmatrix} + ie^{2t} \begin{bmatrix} \sin 2t - 2 \cos 2t \\ -\sin 2t \end{bmatrix}.$$

We only need **real** linearly independent solutions, so:

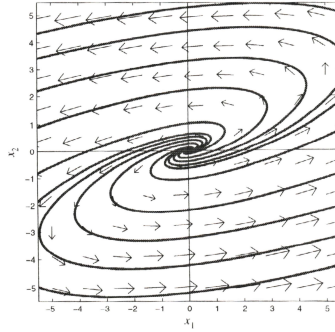
$$\vec{x}(t) = c_1 e^{2t} \begin{bmatrix} \cos 2t + 2 \sin 2t \\ -\cos 2t \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} \sin 2t - 2 \cos 2t \\ -\sin 2t \end{bmatrix}.$$

Or, with alternate notation:

$$\begin{aligned} x_1(t) &= e^{2t}[c_1(\cos 2t + 2 \sin 2t) + c_2(\sin 2t - 2 \cos 2t)] \\ &= e^{2t}[(c_1 - 2c_2) \cos 2t + (2c_1 + c_2) \sin 2t] \end{aligned}$$

$$x_2(t) = e^{2t}(-c_1 \cos 2t - c_2 \sin 2t).$$

The image below shows a direction field for this DEQ and some typical solution curves:



Problem 2 Apply the eigenvalue method to find a general solution of the system.

$$x'_1 = 5x_1 + 5x_2 + 2x_3, \quad x'_2 = -6x_1 - 6x_2 - 5x_3, \quad x'_3 = 6x_1 + 6x_2 + 5x_3$$

Solution: $\mathbf{A} = \begin{bmatrix} 5 & 5 & 2 \\ -6 & -6 & -5 \\ 6 & 6 & 5 \end{bmatrix}$. So characteristic equation: $|\mathbf{A} - \lambda I| = -\lambda^3 + 4\lambda^2 - 13\lambda = 0$

Eigenvalues: $\lambda = 0$ and $2 \pm 3i$. With $\lambda = 0$ the eigenvector equation:

$$\begin{bmatrix} 5 & 5 & 2 \\ -6 & -6 & -5 \\ 6 & 6 & 5 \end{bmatrix} \vec{v}_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \text{ gives eigenvector } \vec{v}_1 = \begin{bmatrix} 1 & -1 & 0 \end{bmatrix}^T.$$

So: $\vec{v}_1 e^{0t} = \begin{bmatrix} 1 & -1 & 0 \end{bmatrix}^T$. With $\lambda = 2 + 3i$ we solve the eigenvector equation...

$$\begin{bmatrix} 5 - (2 + 3i) & 5 & 2 \\ -6 & -6 - (2 + 3i) & -5 \\ 6 & 6 & 5 - (2 + 3i) \end{bmatrix} = \begin{bmatrix} 3 - 3i & 5 & 2 \\ -6 & -8 - 3i & -5 \\ 6 & 6 & 3 - 3i \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 6 & 6 & 3 - 3i \\ -6 & -8 - 3i & -5 \\ 3 - 3i & 5 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & \frac{1}{2} - \frac{1}{2}i \\ 0 & -2 - 3i & -2 - 3i \\ 3 - 3i & 5 & 2 \end{bmatrix}$$

Note: $-(3 - 3i)(\frac{1}{2} - \frac{1}{2}i) = -(\frac{3}{2} - \frac{3}{2} - \frac{3}{2}i - \frac{3}{2}i) = 3i$. So:

$$\Rightarrow \begin{bmatrix} 1 & 1 & \frac{1}{2} - \frac{1}{2}i \\ 0 & -2 - 3i & -2 - 3i \\ 0 & 2 + 3i & 2 + 3i \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & \frac{1}{2} - \frac{1}{2}i \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & -\frac{1}{2} - \frac{1}{2}i \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$z = c, \quad y = -c, \quad x = \frac{c}{2} + \frac{c}{2}i.$$

$$\begin{bmatrix} \frac{c}{2} + \frac{c}{2}i \\ -c \\ c \end{bmatrix} = \begin{bmatrix} 1 + 1i \\ -2 \\ 2 \end{bmatrix} \text{ where } c = 2. \text{ Complex valued eigenvector: } \vec{v}_2 = \begin{bmatrix} 1 + i & -2 & 2 \end{bmatrix}^T.$$

The corresponding complex-valued solution is

$$\vec{v}_2 e^{(2+3i)t} = e^{2t} e^{3it} \begin{bmatrix} 1+i \\ -2 \\ 2 \end{bmatrix} = e^{2t} (\cos 3t + i \sin 3t) \begin{bmatrix} 1+i \\ -2 \\ 2 \end{bmatrix}$$

$$= e^{2t} \begin{bmatrix} (\cos 3t + i \sin 3t) + i(\cos 3t + i \sin 3t) \\ -2 \cos 3t - 2i \sin 3t \\ 2 \cos 3t + 2i \sin 3t \end{bmatrix} = e^{2t} \begin{bmatrix} \cos 3t - \sin 3t + i \cos 3t - i \sin 3t \\ -2 \cos 3t - 2i \sin 3t \\ 2 \cos 3t + 2i \sin 3t \end{bmatrix}.$$

We are only interested in real values, so: $c_2 e^{2t} \begin{bmatrix} \cos 3t - \sin 3t \\ -2 \cos 3t \\ 2 \cos 3t \end{bmatrix} + c_3 e^{2t} \begin{bmatrix} \cos 3t - \sin 3t \\ -2 \sin 3t \\ 2 \sin 3t \end{bmatrix}.$

Finally, we add the three solutions, with arbitrary constants.

$$\text{So: } \vec{x} = c_1 \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} \cos 3t - \sin 3t \\ -2 \cos 3t \\ 2 \cos 3t \end{bmatrix} + c_3 e^{2t} \begin{bmatrix} \cos 3t - \sin 3t \\ -2 \sin 3t \\ 2 \sin 3t \end{bmatrix}.$$

The **scalar components** of the above general solution are:

$$x_1(t) = c_1 + e^{2t} [(c_2 + c_3) \cos 3t - (c_2 + c_3) \sin 3t],$$

$$x_2(t) = -c_1 + 2e^{2t} (-c_2 \cos 3t - c_3 \sin 3t),$$

$$x_3(t) = 2e^{2t} (c_2 \cos 3t + c_3 \sin 3t).$$

Problem 3: Open Three Tank System. Freshwater flows into tank-1. Mixed brine (salt water)

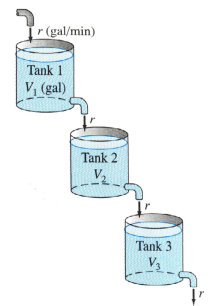
flows from tank-1 into tank-2, from tank-2 into tank-3, and out of tank-3. (see image)

All have flow rate $r = 60$ gallons per minute. Initial ($t = 0$) amounts of salt are:

$$x_1(0) = 40 \text{ lb}, \quad x_2(0) = 0, \quad \text{and} \quad x_3(0) = 0 \text{ in the three tanks.}$$

Initial volumes: $V_1 = 20, \quad V_2 = 12, \quad V_3 = 60$.

a.) **First, solve for the amounts of salt in the three tanks at time t .**



Solution: Observe that: $x'_i = [IN_i \text{ Salt}] - [OUT_i \text{ Salt}]$
 $= [\text{In-Concentration}_i \times \text{In-Flow}_i] - [\text{Out-Concentration}_i \times \text{Out-Flow}_i]$

$$\text{So, } x'_1 = [0 \times 60] - [\frac{x_1}{20} \times 60] = -3x_1. \quad \text{Similarly: } x'_2 = 3x_1 - 5x_2, \quad \text{and} \quad x'_3 = 5x_2 - x_3.$$

$$\text{And, } \vec{z}' = \begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = \begin{bmatrix} -3x_1 \\ 3x_1 - 5x_2 \\ 5x_2 - x_3 \end{bmatrix} = \begin{bmatrix} -3 & 0 & 0 \\ 3 & -5 & 0 \\ 0 & 5 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \mathbf{A} \vec{z}.$$

The coefficient matrix $\mathbf{A} = \begin{bmatrix} -3 & 0 & 0 \\ 3 & -5 & 0 \\ 0 & 5 & -1 \end{bmatrix}$ has as eigenvalues, its diagonal elements:

$\lambda_1 = -3$, $\lambda_2 = -5$, and $\lambda_3 = -1$ (as with any triangular matrix).

We find the associated e-vecs: $\vec{v}_1 = \begin{bmatrix} -4 & -6 & 15 \end{bmatrix}^T$, $\vec{v}_2 = \begin{bmatrix} 0 & -4 & 5 \end{bmatrix}^T$, $\vec{v}_3 = \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}^T$.

So: $\vec{z} = \vec{v}_1 e^{-3t} + \vec{v}_2 e^{-5t} + \vec{v}_3 e^{-t}$.

Or written as a system:

$$x_1(t) = -4c_1 e^{-3t}$$

$$x_2(t) = -6c_1 e^{-3t} - 4c_2 e^{-5t}$$

$$x_3(t) = 15c_1 e^{-3t} + 5c_2 e^{-5t} + c_3 e^{-t}. \quad \text{Now What?}$$

The init-conds $x_1(0) = 40$, $x_2(0) = 0$, and $x_3(0) = 0$ give us $c_1 = -10$, $c_2 = 15$, $c_3 = 75$. So we have:

$$x_1(t) = 40e^{-3t}$$

$$x_2(t) = 60e^{-3t} - 60e^{-5t}$$

$$x_3(t) = -150e^{-3t} + 75e^{-5t} + 75e^{-t}.$$

b.) Now, determine the maximal amount of salt that tank-3 ever contains.

Solution: Remember from calculus that you can find the local maximums and minimums by taking the derivative of the function, and setting it equal to zero. For tank-3: $x_3'(t) = 450e^{-3t} - 375e^{-5t} - 75e^{-t} = 0$.

Multiplying by nonzero $\frac{1}{75e^{-t}}$: $5e^{-4t} - 6e^{-2t} + 1 = 0$. Factoring this is the (not so) hard part.

$(5e^{-2t} - 1)(e^{-2t} - 1) = 0$. And observe that for the second factor: $e^{-2t} = 1$ when $\ln(e^{-2t}) = \ln(1)$, or equivalently when $-2t = 0$, or $t = 0$.

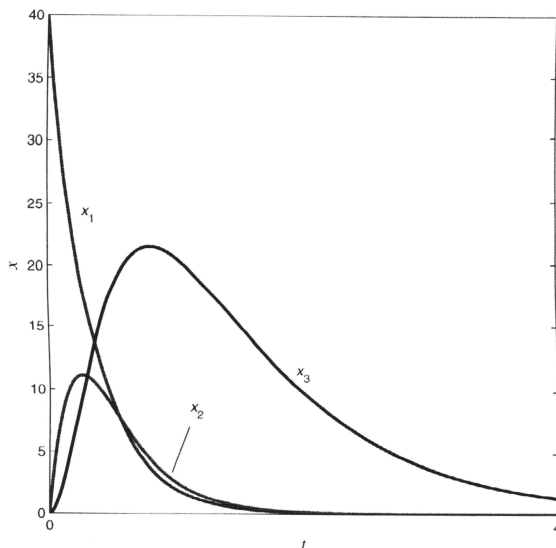
Now looking at the first factor, $e^{-2t} = \frac{1}{5}$ when $\ln(e^{-2t}) = \ln(\frac{1}{5})$,

or when $-2t = -\ln 5$, or $t = \frac{1}{2} \ln 5 \sim 0.8 \text{ min} = 48 \text{ sec}$.

Since $x_3(t) = -150e^{-3t} + 75e^{-5t} + 75e^{-t}$, the max amount of salt ever in tank-3 is $x_3(\frac{1}{2} \ln 5) \approx 21.5 \text{ lbs}$.

c.) Finally, construct a figure showing the graphs of $x_1(t)$, $x_2(t)$, and $x_3(t)$.

Solution: The figure below shows the graph of $x_1(t)$, $x_2(t)$, and $x_3(t)$.



[Adapted from Differential Equations & Linear Algebra, Edwards & Penny]