

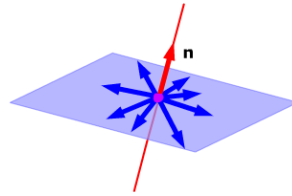
4.2: The Vector Space \mathbb{R}^n and Subspaces

Dimensions $n > 3$, what are they good for?

Time, multiple particle systems, robotics, stock portfolios, local properties (pressure, temperature, color, velocity, etc.).

Vector addition/scalar multiplication in higher dimensions? Analogous to $\mathbb{R}, \mathbb{R}^2, \mathbb{R}^3$.

Subspaces



Subspaces: Given vector space V (e.g., \mathbb{R}^3 in the image above), then W (the plane in the image) is a subset of V , and is called a subspace if:

- ◆ W is nonempty (it contains at least one vector),
- ◆ Given $\vec{u}, \vec{v} \in W$, we have $\vec{u} + \vec{v} \in W$, (W is closed under addition)
- ◆ Given $c \in \mathbb{R}$, we have $c\vec{u} \in W$. (W is closed under scalar multiplication)

And therefore $\vec{0} \in W$. Why?

Also, convince yourself that the x -axis and the y -axis (just the axes themselves, no other points), joined together as a subset of \mathbb{R}^3 , does not constitute a subspace.

Solution Subspace Theorem: For $\mathbf{A}^{m \times n}$, the solution set of the homogeneous linear system

$$\mathbf{A}\vec{x} = \vec{0} \text{ is a subspace of } \mathbb{R}^n.$$

Proof: Let W denote the solution set of the system. If \vec{u} and \vec{v} are vectors in W , then $\mathbf{A}\vec{u} = \mathbf{A}\vec{v} = \vec{0}$.

$$\text{Hence: } \mathbf{A}(\vec{u} + \vec{v}) = \mathbf{A}\vec{u} + \mathbf{A}\vec{v} = \vec{0} + \vec{0} = \vec{0}.$$

Thus the sum $\vec{u} + \vec{v}$ is also in W , and hence W is closed under addition.

$$\text{Next, if } c \in \mathbb{R}, \text{ then } \mathbf{A}(c\vec{u}) = c(\mathbf{A}\vec{u}) = c\vec{0} = \vec{0}.$$

Thus $c\vec{u}$ is in W if \vec{u} is in W . Hence W is also closed under scalar multiplication.

Therefore, W is a subspace of \mathbb{R}^n . ■

Nonhomogeneous System Solutions Theorem: The solution set of a nonhomogeneous system $A\vec{x} = \vec{b}$ is **never** a subspace.

Proof: Let's do proof by contradiction. Let \vec{u} be a solution in W , the set of solutions to the nonhomogeneous system above. And let us make the dubious assumption that W is a subspace.

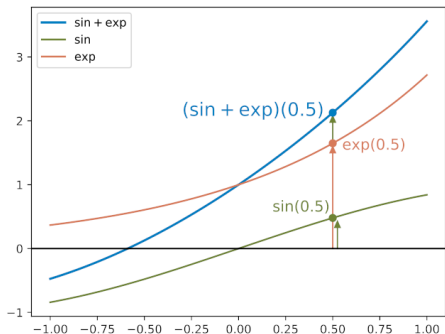
Let $c = 0 \in \mathbb{R}$. By closure under scalar multiplication, $c\vec{u} = 0\vec{u} = \vec{0}$ is a solution.

Therefore, $A\vec{0} = \vec{0} = \vec{b}$. But we assumed the system was nonhomogeneous: $\vec{b} \neq \vec{0}$.

So we have a contradiction, and our assumption that the set of solutions W was a subspace was incorrect. ■

An alternative proof is provided in the book.

Function Spaces



Vector Space of Functions:

Let $F = \{ \text{all real valued functions} \}$; includes all polynomials, trig functions, exponentials, etc...

Observe that for \mathbf{f}, \mathbf{g} in F , we have: $\mathbf{f}(x) + \mathbf{g}(x) = (\mathbf{f} + \mathbf{g})(x)$ and $c(\mathbf{f}(x)) = (c\mathbf{f})(x)$, which are also real valued functions.

The other properties of a vector space follow from the fact that these functions are real valued. The textbook proves one of the properties.

Video Tutorial (visually rich and intuitive): https://youtu.be/fNk_zzaMoSs

Exercises

Problem: #16 For the following system of equations, find two solution vectors \vec{u} and \vec{v} (a basis) such that the **solution space** is the set of all linear combinations of the form $s\vec{u} + t\vec{v}$.

$$\begin{aligned} x_1 - 4x_2 - 3x_3 - 7x_4 &= 0 \\ 2x_1 - x_2 + x_3 + 7x_4 &= 0 \end{aligned}$$

$$x_1 + 2x_2 + 3x_3 + 11x_4 = 0$$

$$\mathbf{A} = \begin{bmatrix} 1 & -4 & -3 & -7 \\ 2 & -1 & 1 & 7 \\ 1 & 2 & 3 & 11 \end{bmatrix} \xrightarrow{\text{trust me}} \begin{bmatrix} 1 & 0 & 1 & 5 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Thus, $x_3 = s$ and $x_4 = t$ are free variables. We solve for $x_2 = -s - 3t$, and $x_1 = -s - 5t$. So ...

$$\vec{x} = (x_1, x_2, x_3, x_4) = (-s - 5t, -s - 3t, s, t)$$

$$= (-s, -s, s, 0) + (-5t, -3t, 0, t) = s\vec{u} + t\vec{v}, \text{ where } \vec{u} = (-1, -1, 1, 0) \text{ and } \vec{v} = (-5, -3, 0, 1).$$

Problem: #22 Reduce the given system to echelon form to find a single solution vector \vec{u} such that the solution space is the set of all scalar multiples of \vec{u} .

$$\begin{aligned} x_1 + 3x_2 + 3x_3 + 3x_4 &= 0, \\ 2x_1 + 7x_2 + 5x_3 - x_4 &= 0, \\ 2x_1 + 7x_2 + 4x_3 - 4x_4 &= 0. \end{aligned}$$

$$\mathbf{A} = \begin{bmatrix} 1 & 3 & 3 & 3 \\ 2 & 7 & 5 & -1 \\ 2 & 7 & 4 & -4 \end{bmatrix} \xrightarrow{\text{trust me}} \begin{bmatrix} 1 & 0 & 0 & 6 \\ 0 & 1 & 0 & -4 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

Thus $x_4 = t$ is a parameter (a.k.a. free variable).

We solve for $x_1 = -6t$, $x_2 = 4t$, and $x_3 = -3t$. So,

$$\vec{x} = (x_1, x_2, x_3, x_4) = (-6t, 4t, -3t, t) = t\vec{u}, \text{ where } \vec{u} = (-6, 4, -3, 1).$$

Problem: #29 Let \mathbf{A} be an $n \times n$ matrix, \vec{b} be a nonzero vector, and \vec{x}_0 be a solution vector to the system $\mathbf{A}\vec{x} = \vec{b}$. Show that \vec{x}_2 is another solution **if and only if** $(\Leftrightarrow) \vec{x}_2 - \vec{x}_0$ is a solution of the homogeneous system $\mathbf{A}\vec{y} = \vec{0}$.

We are given: $\mathbf{A}\vec{x}_0 = \vec{b}$.

Need to show that: $\mathbf{A}\vec{x}_2 = \vec{b} \Leftrightarrow \mathbf{A}(\vec{x}_2 - \vec{x}_0) = \vec{0}$.

Starting with the left assumption, and trying to show the thing on the right, we have:

$$\mathbf{A}(\vec{x}_2 - \vec{x}_0) = \mathbf{A}\vec{x}_2 - \mathbf{A}\vec{x}_0 = \vec{b} - \vec{b} = \vec{0}. \quad \checkmark$$

Going from right to left, we have: $\mathbf{A}(\vec{x}_2 - \vec{x}_0) = \mathbf{A}\vec{x}_2 - \mathbf{A}\vec{x}_0 = \mathbf{A}\vec{x}_2 - \vec{b} = \vec{0}$, therefore $\mathbf{A}\vec{x}_2 = \vec{b}$.

Q.E.D.

Problem: #6. Assume W is the set of all vectors in \mathbb{R}^4 such that $x_1 = 3x_3$ and $x_2 = 4x_4$. Apply the theorems in this section to determine whether or not W is a subspace of \mathbb{R}^4 .

$$W = \{(3c, 4d, c, d)\}.$$

First, note that the subspace is nonempty since $(3, 4, 1, 1) \in W$, where $c, d = 1$.

We arbitrarily choose two vectors from W by arbitrarily choosing four constant $c_1, d_1, c_2, d_2 \in \mathbb{R}$, giving us $(3c_1, 4d_1, c_1, d_1)$ and $(3c_2, 4d_2, c_2, d_2)$. We then test them for closure under addition:

$$\begin{aligned} &(3c_1, 4d_1, c_1, d_1) + (3c_2, 4d_2, c_2, d_2) \\ &= (3c_1 + 3c_2, 4d_1 + 4d_2, c_1 + c_2, d_1 + d_2) \\ &= (3(c_1 + c_2), 4(d_1 + d_2), c_1 + c_2, d_1 + d_2) \in W \end{aligned}$$

This is because it has the prescribed format $\{(3c, 4d, c, d)\}$, where $c = c_1 + c_2$ and $d = d_1 + d_2$.

Now to test scalar multiplication:

$$\begin{aligned} \alpha(3c_1, 4d_1, c_1, d_1) &= (3\alpha c_1, 4\alpha d_1, \alpha c_1, \alpha d_1) \in W = \{(3c, 4d, c, d)\} \\ &\text{where } c = \alpha c_1 \text{ and } d = \alpha d_1. \end{aligned}$$

Therefore, W is nonempty, closed under addition, and scalar multiplication, and is a subspace of \mathbb{R}^4 . ■