

3.5 Completing the Square

Determining the Positive Definiteness of a Matrix

"Completing the square" has previously assisted you in deriving the quadratic formula, and later for integrating various types of rational and algebraic functions.

Given: $q(x) = ax^2 + 2bx + c = 0$

$$q(x) = a\left(x + \frac{b}{a}\right)^2 + \frac{ac-b^2}{a} = 0.$$

As a result: $\left(x + \frac{b}{a}\right)^2 = \frac{b^2-ac}{a^2}$ and $x = \frac{-b \pm \sqrt{b^2-ac}}{a}$.

Similarly: given $q(x_1, x_2) = ax_1^2 + 2bx_1x_2 + cx_2^2$, where $a \neq 0$,

$$\begin{aligned} q(x_1, x_2) &= a\left(x_1 + \frac{b}{a}x_2\right)^2 + \frac{ac-b^2}{a}x_2^2 \\ &= ay_1^2 + \frac{ac-b^2}{a}y_2^2, \end{aligned} \tag{1}$$

where $y_1 = x_1 + \frac{b}{a}x_2$ and $y_2 = x_2$. (2)

Expression (1) is positive definite in y_1, y_2 if $a > 0$ and $\frac{ac-b^2}{a} > 0$.

This would mean, $q(x_1, x_2) \geq 0$. We get equality **iff**

$$y_1 = y_2 = 0 \quad \Leftrightarrow \quad x_1 = x_2 = 0.$$

Goal: Generalize to More Variables

Observe quadratic form $q(x_1, x_2)$ above can be rewritten as: $\vec{x}^T \mathbf{K} \vec{x}$, where $\mathbf{K} =$??

$$\mathbf{K} = \begin{bmatrix} a & b \\ b & c \end{bmatrix}, \quad \vec{x} := \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}.$$

RHS of (1) can be written as $\hat{q}(\vec{y}) := \vec{y}^T \mathbf{D} \vec{y}$, (3)

$$\text{where } \mathbf{D} := \begin{bmatrix} a & 0 \\ 0 & \frac{ac-b^2}{a} \end{bmatrix}, \quad \vec{y} := \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}.$$

From (2), we can write $\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 + \frac{b}{a}x_2 \\ x_2 \end{bmatrix}$ or $\vec{y} = \mathbf{L}^T \vec{x}$ where $\mathbf{L}^T := \begin{bmatrix} 1 & \frac{b}{a} \\ 0 & 1 \end{bmatrix}$.

Substituting this into (3), we obtain: $\vec{y}^T \mathbf{D} \vec{y} = (\mathbf{L}^T \vec{x})^T \mathbf{D} (\mathbf{L}^T \vec{x})$

$$= \vec{x}^T \mathbf{L} \mathbf{D} \mathbf{L}^T \vec{x} = \vec{x}^T \mathbf{K} \vec{x}, \text{ where } \mathbf{K} = \mathbf{L} \mathbf{D} \mathbf{L}^T. \quad (4)$$

In other words, given $q(\vec{x})$ (and therefore \mathbf{K}), you can complete the square by calculating the \mathbf{LDL}^T decomposition of \mathbf{K} .

(D gives you the coefficients, and L gives you the squared quantities of (1))

A previous theorem says that regular symmetric matrices are precisely those that admit an \mathbf{LDL}^T decomposition. Therefore (4) is valid for all regular symmetric matrices.

This allows us to write a quadratic form as a sum of squares: $q(\vec{x}) = \vec{x}^T \mathbf{K} \vec{x} = \vec{y}^T \mathbf{D} \vec{y} = d_1 y_1^2 + \dots + d_n y_n^2$, where $\vec{y} = \mathbf{L}^T \vec{x}$.

The d_i are the diagonal entries of \mathbf{D} , the pivots of \mathbf{K} . So:

Regular & Symmetric $\Rightarrow \mathbf{LDL}^T$ factorable \Rightarrow "Complete the square-able"

"Complete the square-able" and $d_i > 0 \Rightarrow$ Pos. def.

How about with more variable?

Theorem: Given a symmetric $\mathbf{K}^{n \times n}$, it is positive definite **iff** it is regular and has all positive pivots.

Proof: If upper left k_{11} (first pivot) is not strictly positive, \mathbf{K} cannot be positive definite because $q(\vec{e}_1) = \vec{e}_1^T \mathbf{K} \vec{e}_1 = k_{11} \leq 0$.

Otherwise, suppose $k_{11} > 0$. We can write: $q(\vec{x}) = \vec{x}^T \mathbf{K} \vec{x}$

$$= (k_{11}x_1^2 + 2k_{12}x_1x_2 + \dots + 2k_{1n}x_1x_n) + \dots + (k_{22}x_2^2 + 2k_{23}x_2x_3 + \dots + 2k_{2n}x_2x_n) + \dots + (2k_{1n}x_1x_n + \dots + k_{nn}x_n^2)$$

$$= k_{11} \left(x_1 + \frac{k_{12}}{k_{11}}x_2 + \dots + \frac{k_{1n}}{k_{11}}x_n \right)^2 + \tilde{q}(x_2, \dots, x_n)$$

$$= k_{11}(x_1 + \ell_{21}x_2 + \dots + \ell_{n1}x_n)^2 + \tilde{q}(x_2, \dots, x_n). \quad (5)$$

Claim: $q(\vec{x})$ is positive definite **iff** \tilde{q} is positive definite. (must show both directions \Leftarrow & \Rightarrow)

\Leftarrow Indeed, if \tilde{q} is positive definite and $k_{11} > 0$, then $q(\vec{x})$ is the sum of two positive quantities, which simultaneously vanish **iff** $x_1 = x_2 = \dots = x_n = 0$.

\Rightarrow Showing contrapositive, suppose $\tilde{q}(x_2^*, \dots, x_n^*) \leq 0$ for some x_2^*, \dots, x_n^* , not all zero.

Setting $x_1^* = -\ell_{21}x_2^* - \dots - \ell_{n1}x_n^*$ makes the initial square term in (5) equal to zero,

$$\text{so } q(x_2^*, \dots, x_n^*) = \tilde{q}(x_2^*, \dots, x_n^*) \leq 0. \quad \blacksquare$$

Cholesky Factorization is cool, but I won't test you on it.